

# Logistics and Introduction

CS 480

Intro to Artificial Intelligence

# Course Info

CS 480-001 Introduction to Artificial Intelligence

**When:** Tuesdays/Thursdays, 10:30-11:45am

**Where:** Horizon hall, room 2009

**Course syllabus:** <https://cs.gmu.edu/~hrolenok/teaching/cs-480-spring2025/index.html>

**Instructor:** Brian Hrolenok

Instructor office hours: Date/Time TBD, ENGR 4708

# Topics

- Search
- Bayes Nets
- Filtering
- Markov Decision Processes and Reinforcement Learning
- Local Search / Optimization (maybe)
- Regression
- Neural Networks
- Decision Trees

Readings and tentative schedule on the syllabus



# Grading

- 7 problem sets (10% total, on Gradescope now)
- 4 homeworks (30% total, on Gradescope (first one available now))
- 1 midterm (25%, roughly week 9)
- 1 final (35%, scheduled by the registrar)

Midterm will be closed-book with 1 page of notes, individual work only.

Final will be closed-book with 2 pages of notes, individual work only.

Assignments can be done in groups of **at most 3**. The homework assignments are autograded, and the autograder is available to you. Problem sets are graded by hand.

See the syllabus for details

# Prerequisites

Official prereq's: CS 310, CS 330

Useful programming skills to have

- Python
- Objects and Classes
- Data structures
- Algorithms and Complexity

Useful math to know

- Probability
- Calculus
- Linear Algebra
- Discrete

**If you are unsure, check out the first assignments.**

# What is Artificial Intelligence?

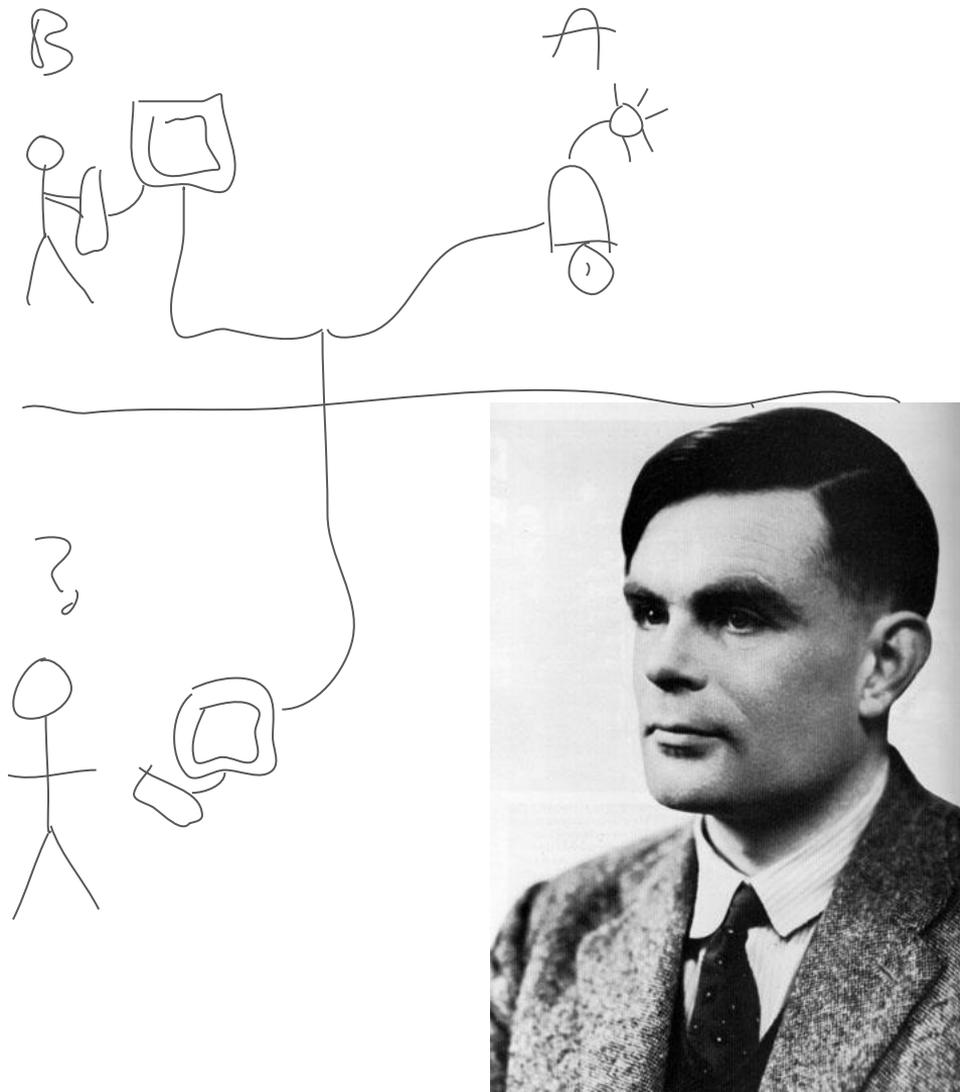
## What is intelligence?

- Thinking like a human
  - Cognitive Science
  - Introspection
  - Difficult to experimentally measure/test
- Acting like a human
  - Turing Test (1950!)
  - Narrow criteria for success
  - Humans make mistakes
  - Do we really understand what “intelligence” means?
- Thinking Rationally
  - “Laws of thought”
  - natural computer implementation
  - Informal vs formal knowledge?
  - Inefficient?
- **Acting rationally**
  - **Agent** based approach
  - Easy\* to define success and experimentally validate
  - Allows for novel artificial solutions (wheels vs feet)

# The Turing Test

- In room 1: a human at a terminal (interrogator)
- In room 2: Two subjects, A and B
  - A human at a terminal
  - An AI program running on a computer
- Only communication allowed via terminal
- Interrogator goal: pick which of A or B is the human and which the computer
- AI goal: fool the interrogator into believing it is the human

Turing's point: if the program can win this game, we **can't** say the computer is **not** intelligent\*

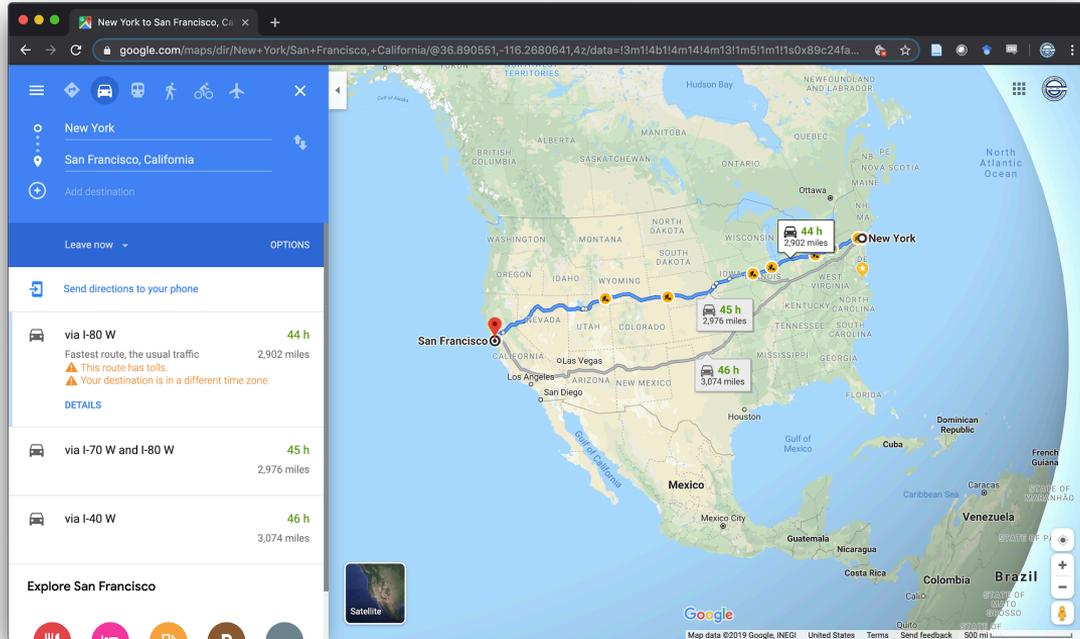


# A brief and incomplete history of AI

- 1950 - Turing Test
- '52 - Checkers (Samuel)
- '56 - The Dartmouth Summer Workshop
- '58 - Lisp (McCarthy)
- '62 - Perceptrons (Rosenblatt, Block)
- '65 - First order logic (Robinson)
- '67 - Algebra word problems (Bobrow)
- '68 - SHRDLU (Winograd)
- '69 - Limits of perceptrons (Minsky)\*
- '70-75 Blocks World (Winston, Sussman, Waltz)
- '74 - Lighthill report, SUR\*
- '80-87 - Expert Systems, commercial success
- '81 - Fifth Generation project launched
- '87 - SCI cutbacks, LISP machine market collapse\*
- '91 - Fifth Generation project canceled\*
- '97 - LSTMs
- '98 - ConvNets for MNIST (LeCun)
- 2009 - Pre-training for DNNs
- 2012 - AlexNet wins ImageNet
- 2015 - AlphaGo, DQN
- 2014-2019 - Google, Facebook, Uber, Amazon, Apple, Netflix...

\*AI “winters”

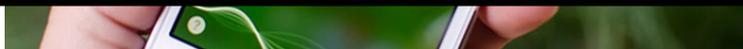
# Where are we today? (1)



## Where are we today? (2)



Home speakers

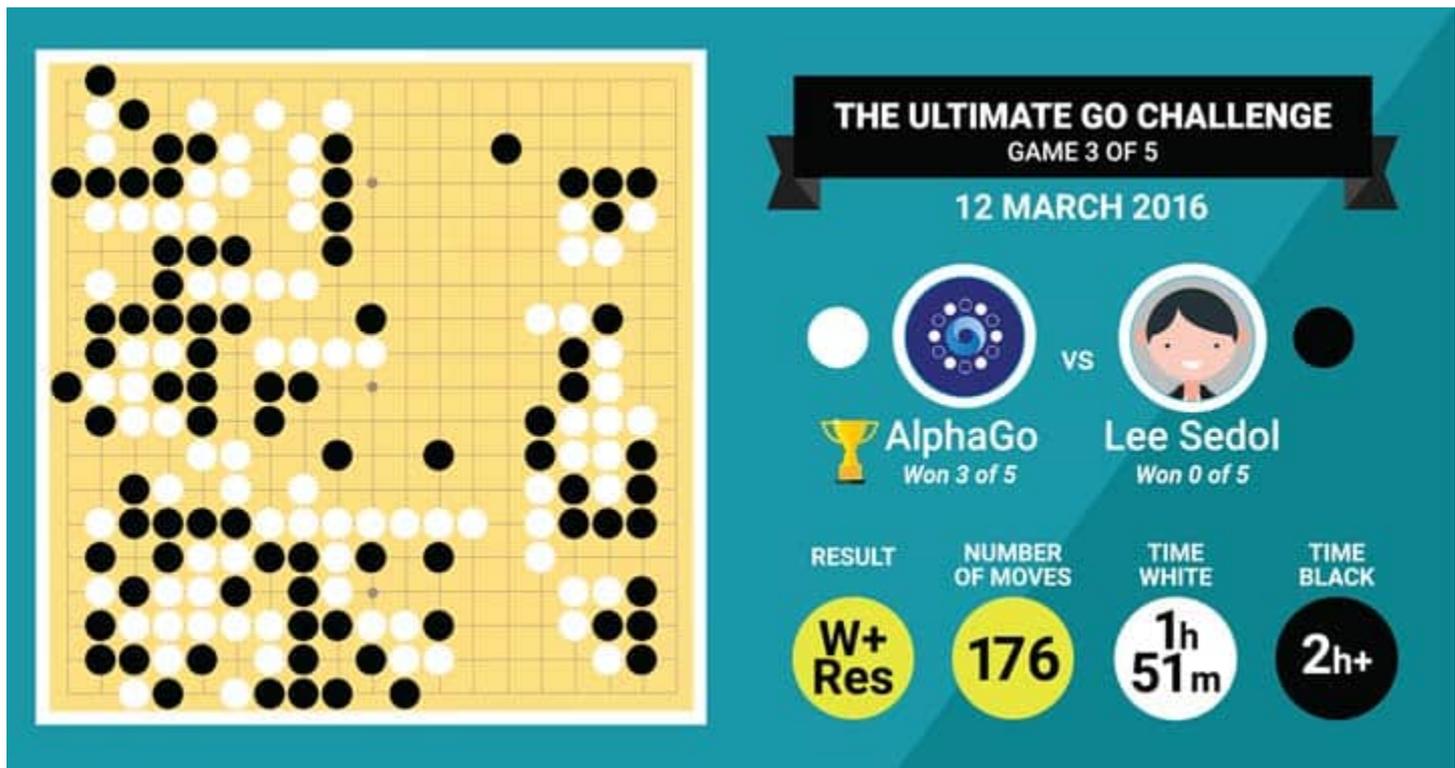


Phone Assistants



Dialog systems

# Where are we today? (3)



# Where are we today? (4)



<https://www.youtube.com/watch?v=5ALIK-z-vUg>

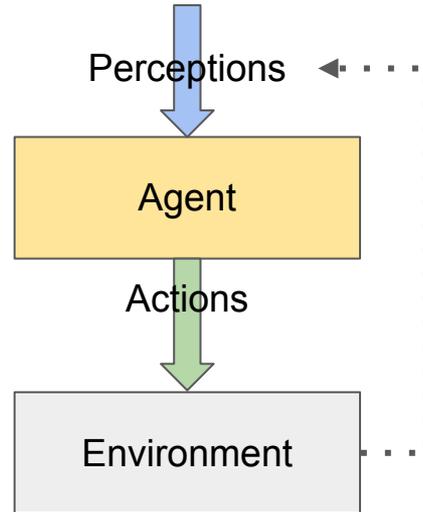
# An Agent-based Approach

An **agent** is an entity that perceives and acts in an **environment**

SENSE

THINK

ACT



# An Agent-based Approach

A mathematical definition of **agent**

$$f : \mathcal{P}^* \rightarrow \mathcal{A}$$

$\mathcal{P}$  perception,  $\mathcal{P}^*$  sequences of perceptions,  $\mathcal{A}$  actions

How do we design a computer program to compute **f()**?

How do we **efficiently** determine the **best** f() for a given task?

# A simple example: Vacuum world

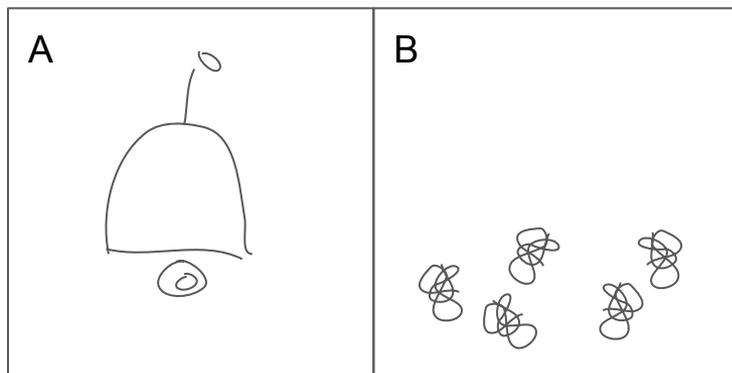
**Environment:** 2 rooms (cells)

**Perceptions:** Which room agent is in, whether the room is clean or dirty

**Actions:** Move left, move right, clean  
Moving into a wall does nothing  
Cleaning a clean room does nothing

**P\*:** [(A,Clean)], [(A,Dirty)], ... [(A,Clean),(B,Dirty)], [(B,Clean)], ...

**Objective:** Both rooms are clean



Current P: (A, Clean)

# For next time

- Write a program to compute  $f()$  for vacuum world
- How simple can we make it?
- What's the **best**  $f()$ ?
- What kinds of things can we do to make the problem more challenging?
- Do we always need the full history of perceptions?
- State space vs. Perception history